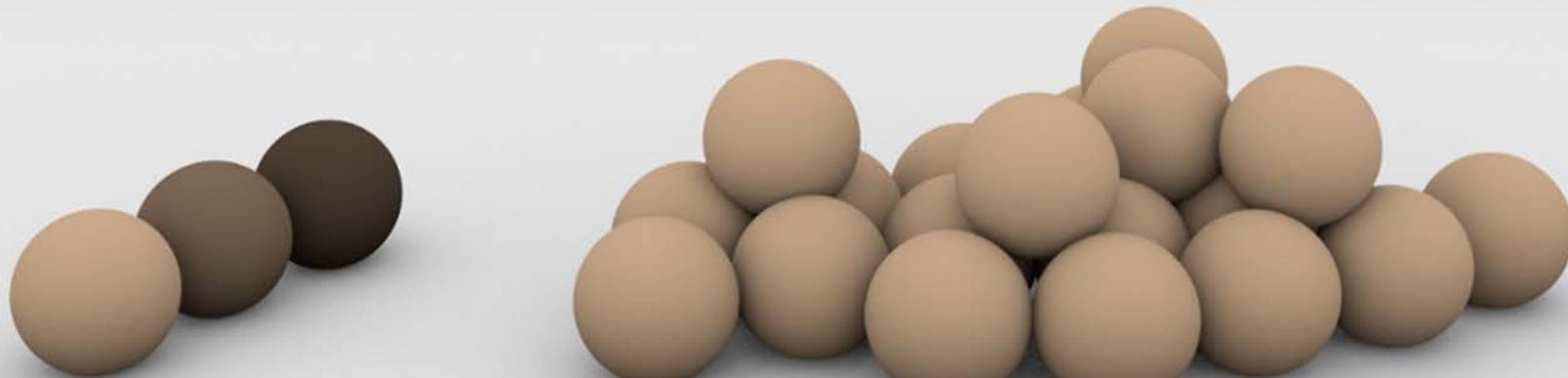


Physical Animation of Wetting Terrain and Erosion

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Comenius University



Supervised by: Doc. RNDr. Roman Ďuríkovič, PhD.

Problem

- terrain erosion
- mass movement



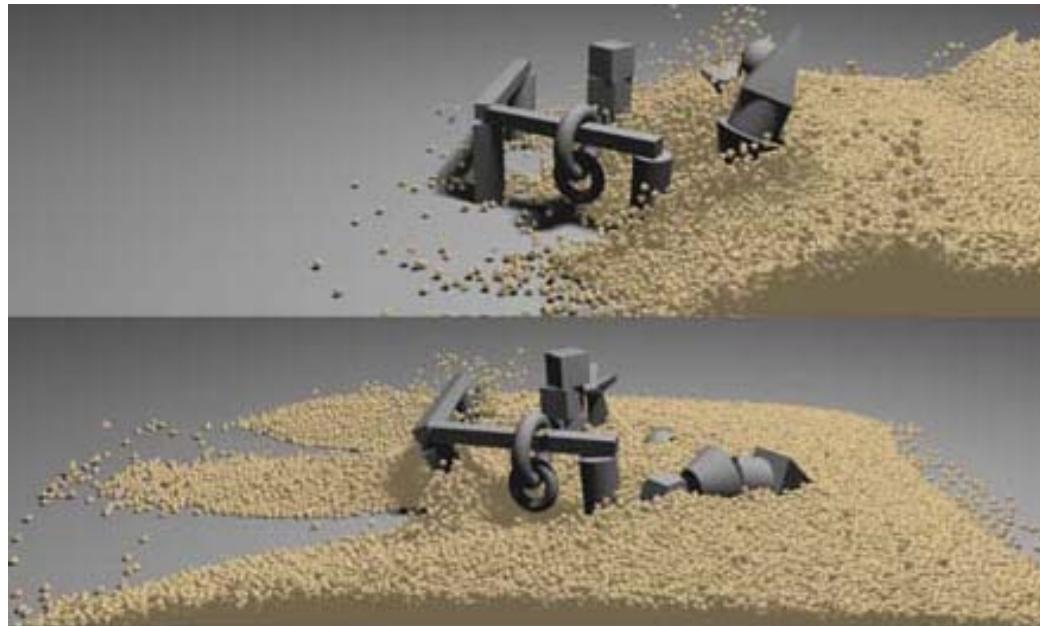
Motivation

- wetness in terrain erosion
- underlying structures
- soil system
- granular material
- particle – based simulation

Related Work

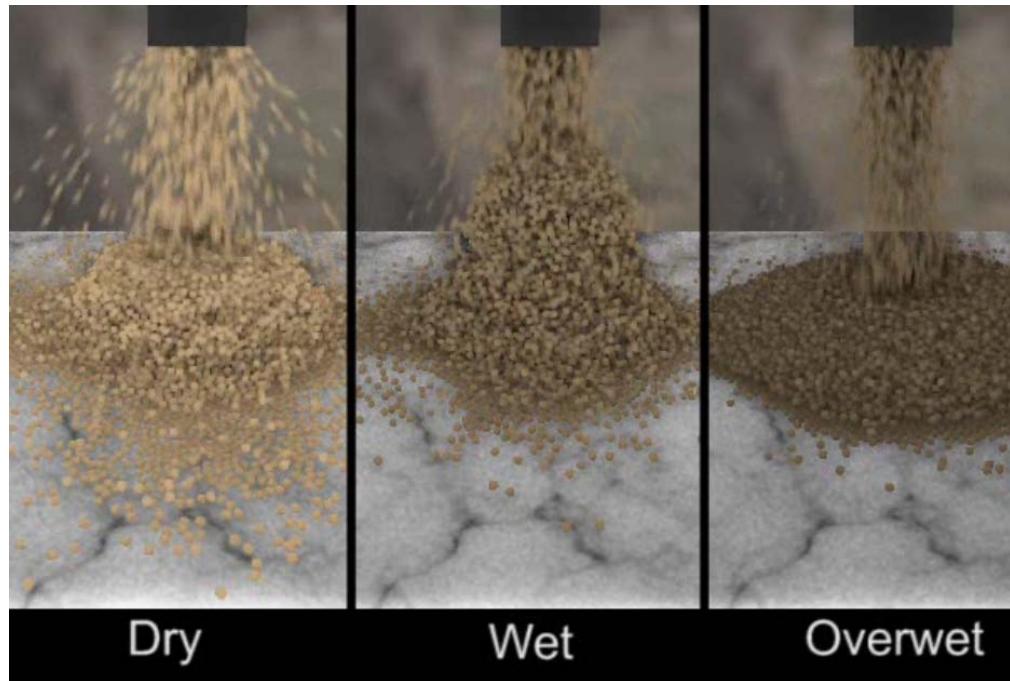
- Cundall [CUN79] - Discrete Element Method
- 2D simulation, falling rigid rocks
- not cohesive
- rigid particles

Related Work II



- DEM revisited by Bell et al. [BYM05]
- different friction forces
- real world friction – angle of repose cca 20° [LEE92]

Related Work III

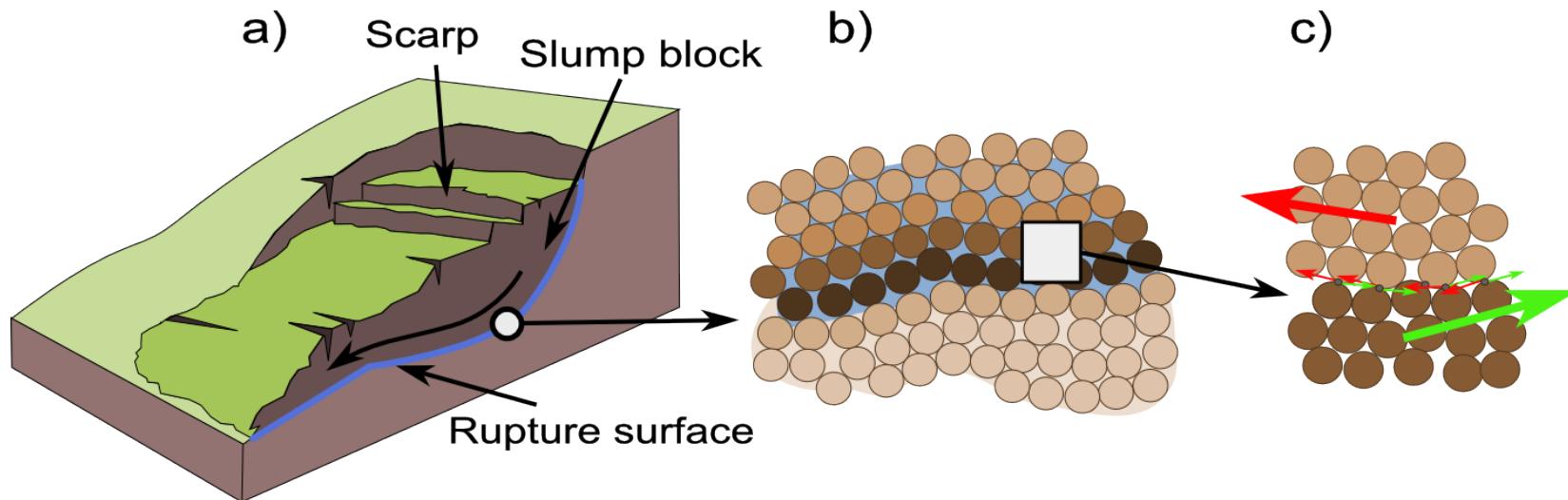


- wetness system. [RUN08]
- particles are dry, wet and overwet
- cohesion, liquid bridge

Our Approach

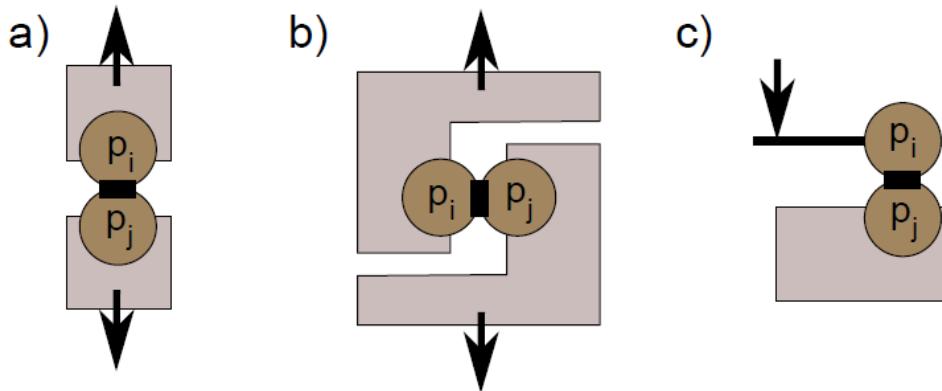
- soil system with DEM
- water system with SPH [CHLA10]
- wetting system
- layers, non homogeneous material
- wetness, cohesion, stability

Assumption



- wetness between layers → mass movement

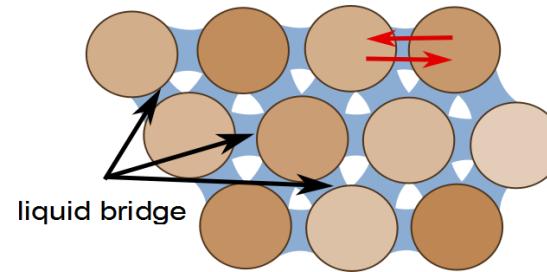
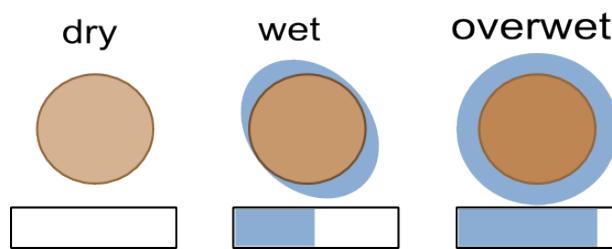
Bonds



$$\vec{B}_n = (R_n/\xi) * \vec{N}$$

- bonding effect in natural sands [JIANG06]
- limitation in DEM contact forces
- normal, tangential, angular
- higher strength, material stability
- most in dry soil

Cohesion

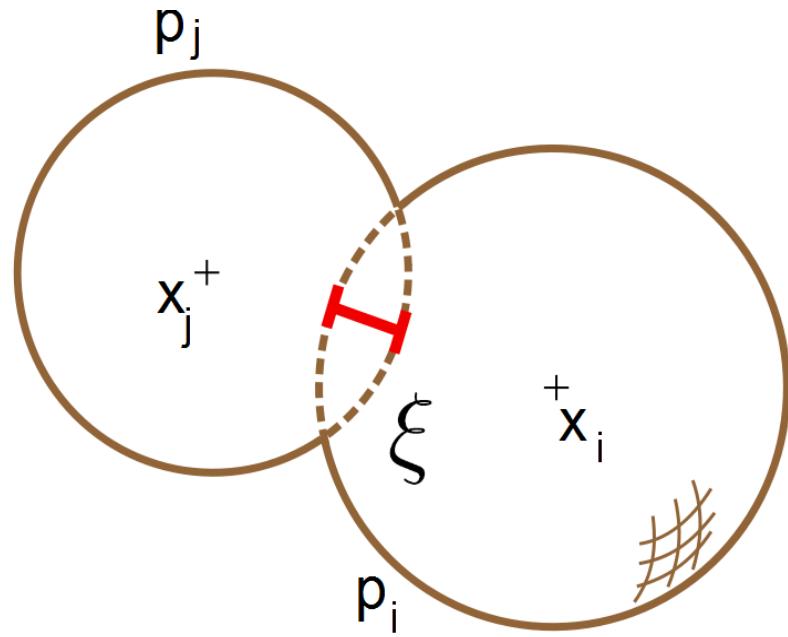


$$\overrightarrow{F_i^{attract}} = \max \left\{ 0, w_f - \frac{w_i + w_j}{2} \right\} (v_j - v_i)$$

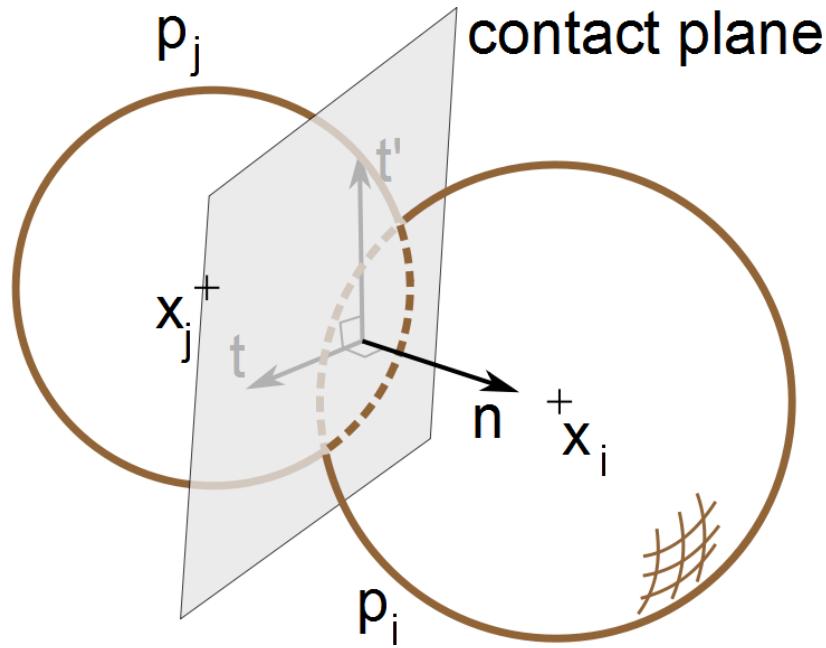
$$w_i^{t+\Delta t} = w_i^t + k_p \frac{\Delta w_i^t}{N_i} \Delta t$$

- wet particles
- liquid bridge
- water particles → wetness contribution
- water aggregation speed
- most in wet material

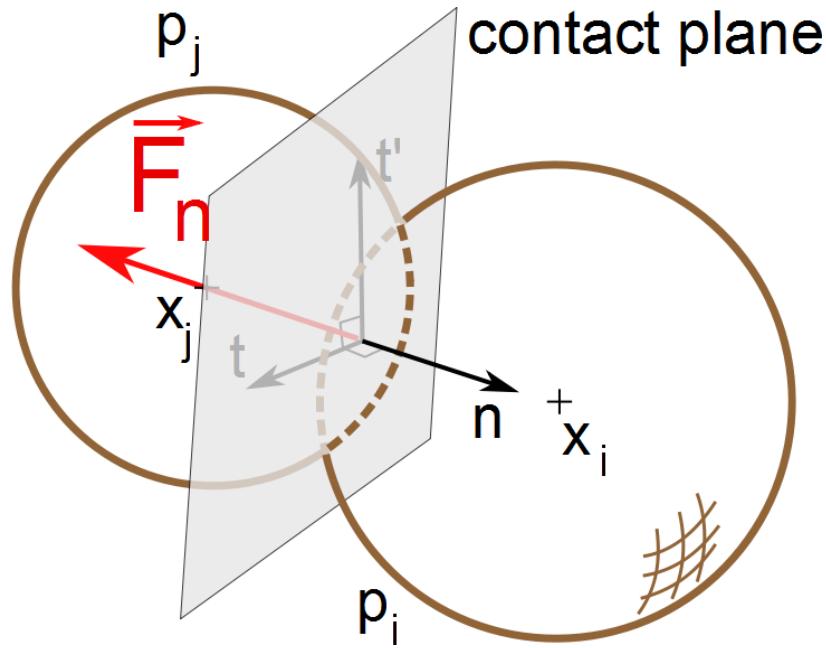
Contact Model Pipeline



Contact Model Pipeline

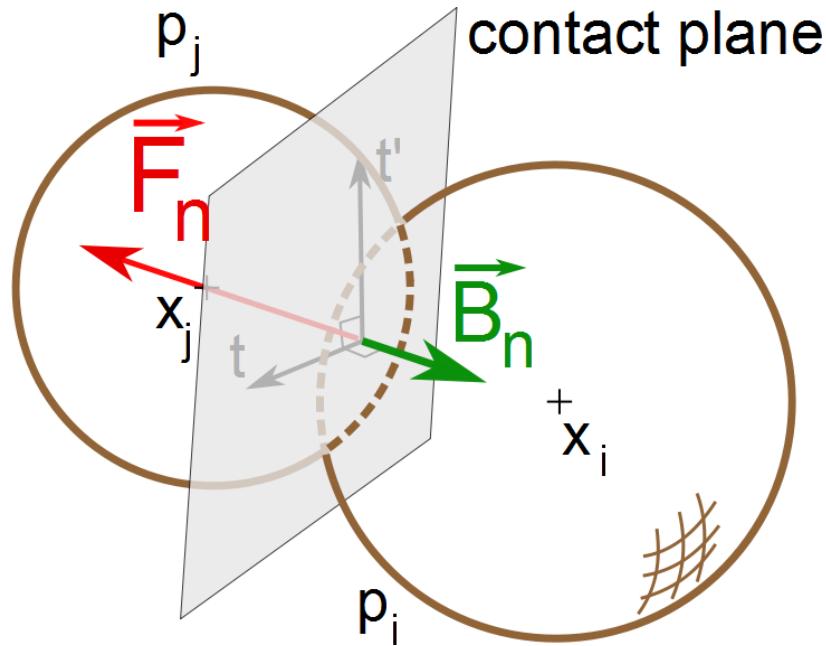


Contact Model Pipeline



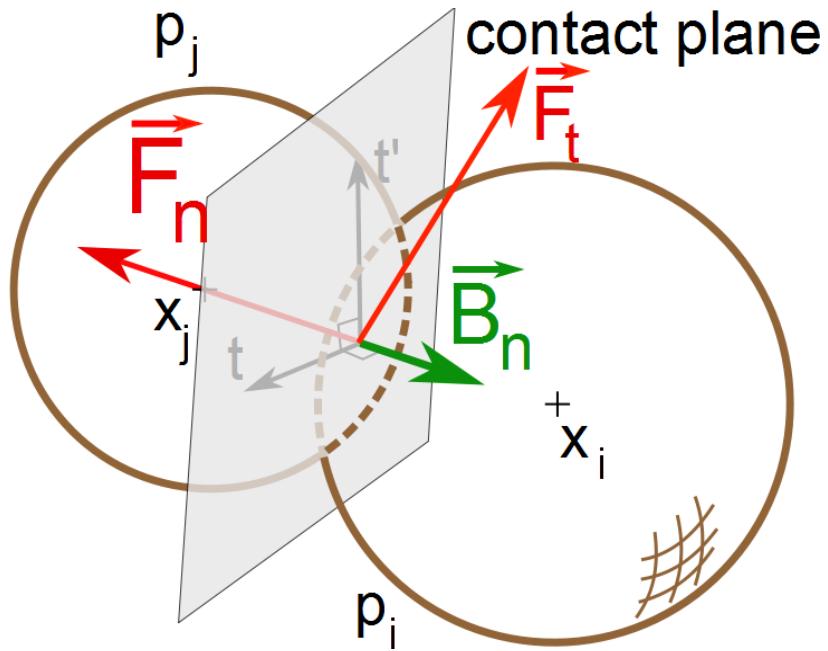
$$\vec{F}_n = k_s \xi \frac{\vec{N}}{\|\vec{N}\|} + k_d \vec{N}$$

Contact Model Pipeline



$$\vec{F}_n = k_s \xi \frac{\vec{N}}{\|\vec{N}\|} + k_d \vec{N} - (R_n / \xi) \vec{N}$$

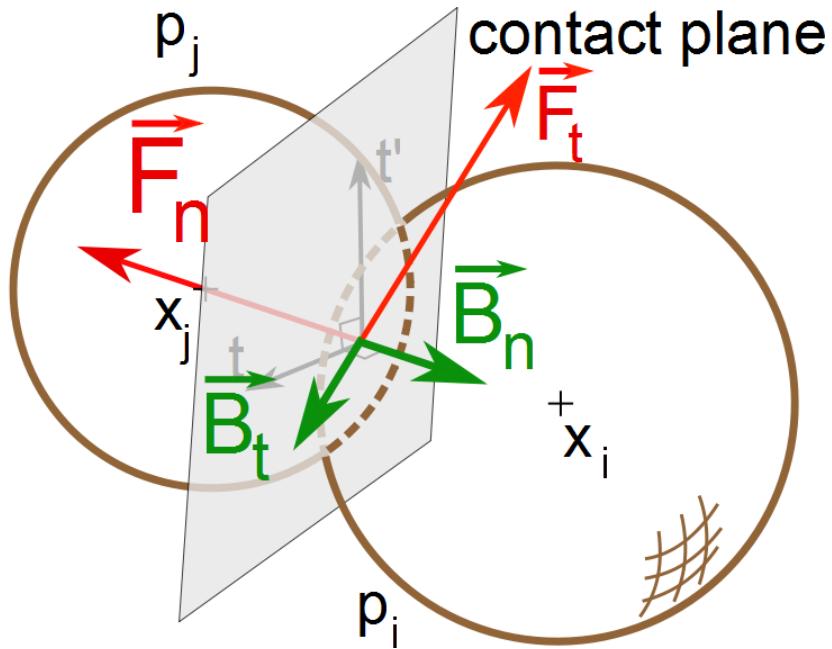
Contact Model Pipeline



$$\vec{F}_n = k_s \xi \frac{\vec{N}}{\|\vec{N}\|} + k_d \vec{N} - (R_n / \xi) \vec{N}$$

$$\vec{F}_t = -\min(\mu f_n, k_t \|\vec{V}_t\|) \frac{\vec{V}_t}{\|\vec{V}_t\|}$$

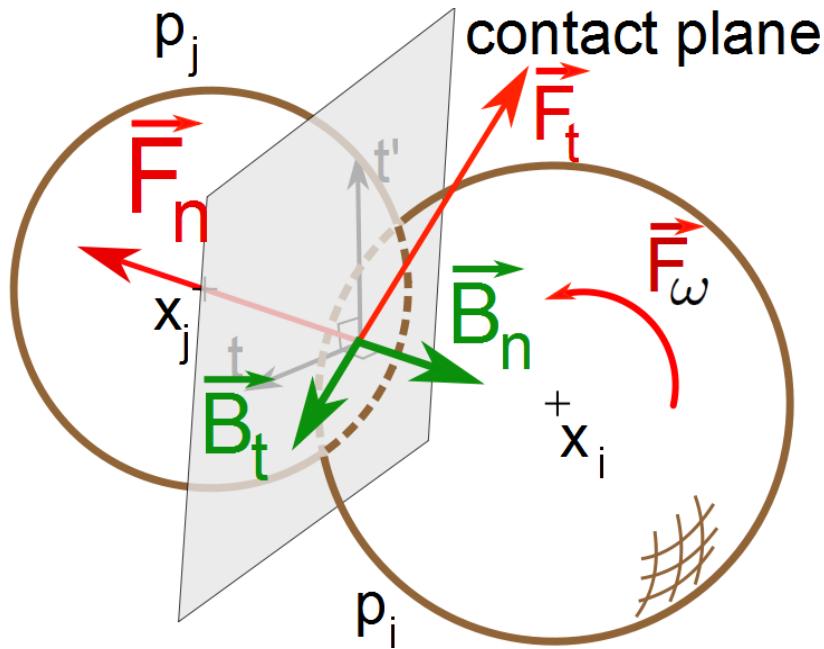
Contact Model Pipeline



$$\vec{F}_n = k_s \xi \frac{\vec{N}}{\|\vec{N}\|} + k_d \vec{N} - (R_n/\xi) \vec{N}$$

$$\vec{F}_t = -\min(\mu f_n, k_t \|\vec{V}_t\|) \frac{\vec{V}_t}{\|\vec{V}_t\|} + (R_t/\xi) \frac{\vec{V}_t}{\|\vec{V}_t\|}$$

Contact Model Pipeline

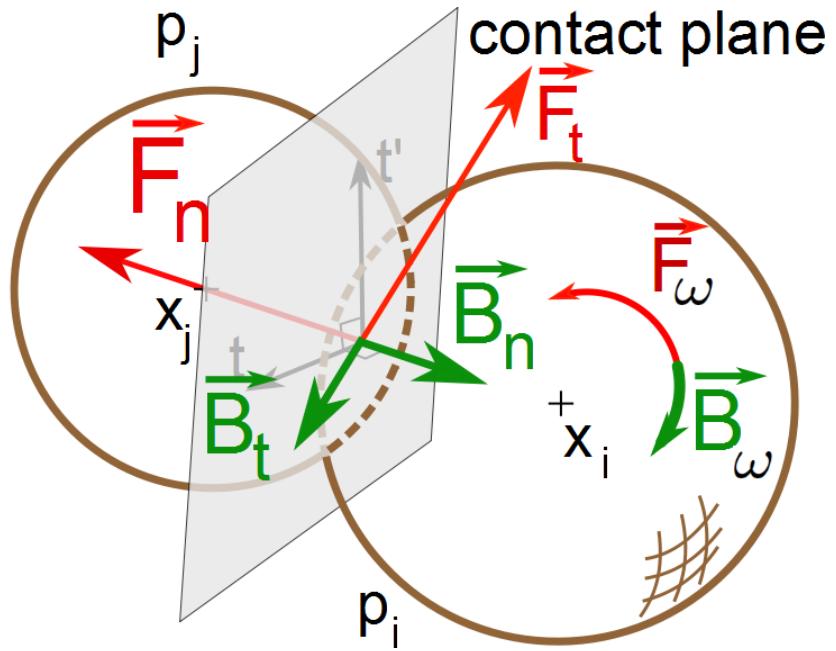


$$\vec{F}_n = k_s \xi \frac{\vec{N}}{\|\vec{N}\|} + k_d \vec{N} - (R_n/\xi) \vec{N}$$

$$\vec{F}_t = -\min(\mu f_n, k_t \|\vec{V}_t\|) \frac{\vec{V}_t}{\|\vec{V}_t\|} + (R_t/\xi) \frac{\vec{V}_t}{\|\vec{V}_t\|}$$

$$\vec{F}_\omega = (\vec{x} - \vec{p}_i) \times \vec{F}_n + (\vec{x} - \vec{p}_i) \times \vec{F}_t$$

Contact Model Pipeline

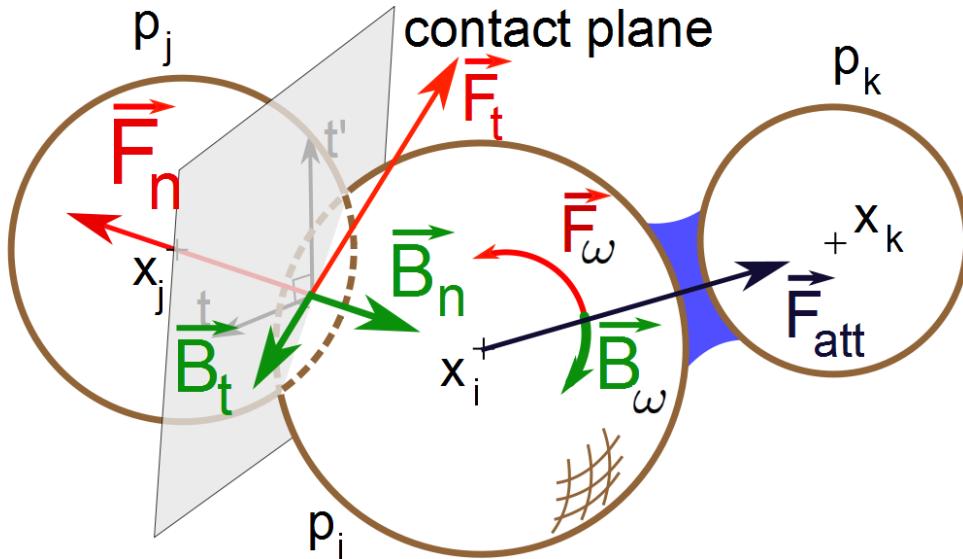


$$\vec{F}_n = k_s \xi \frac{\vec{N}}{\|\vec{N}\|} + k_d \vec{N} - (R_n/\xi) \vec{N}$$

$$\vec{F}_t = -\min(\mu f_n, k_t \|\vec{V}_t\|) \frac{\vec{V}_t}{\|\vec{V}_t\|} + (R_t/\xi) \frac{\vec{V}_t}{\|\vec{V}_t\|}$$

$$\vec{F}_\omega = (\vec{x} - \vec{p}_i) \times \vec{F}_n + (\vec{x} - \vec{p}_i) \times \vec{F}_t - (R_\omega/\xi) \vec{V}_\omega$$

Contact Model Pipeline



$$\vec{F}_n = k_s \xi \frac{\vec{N}}{\|\vec{N}\|} + k_d(1 + w_i + w_j) \vec{N} - (R_n/\xi) \vec{N}$$

$$\vec{F}_t = -\min(\mu(1 + w_i + w_j) f_n, k_t(1 + w_i + w_j) \|\vec{V}_t\|) \frac{\vec{V}_t}{\|\vec{V}_t\|} + (R_t/\xi) \frac{\vec{V}_t}{\|\vec{V}_t\|}$$

$$\vec{F}_\omega = (\vec{x} - \vec{p}_i) \times \vec{F}_n + (\vec{x} - \vec{p}_i) \times \vec{F}_t - (R_\omega/\xi) \vec{V}_\omega$$

$$\vec{F}_i^{attract} = \max \left\{ 0, w_f - \frac{w_i - w_j}{2} \right\} (v_j - v_i)$$

Technical Parameters

Simulation

- C++, QT
- input – Blender + 3D scan line
- CPU, OpenMP

Visualization

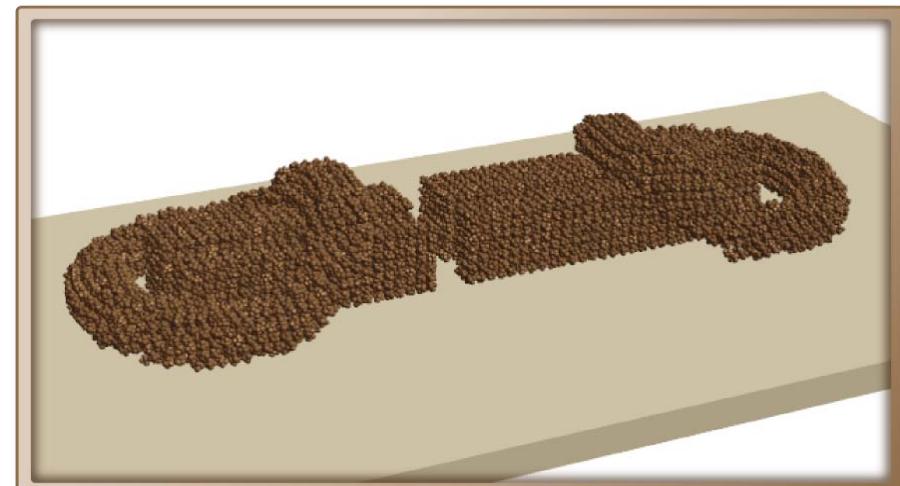
- internal – OpenGL

Results

scene	particles	1 core	openMP	time step
sand	130k	0.2 fps	6 fps	0.001
wetness	20k	7 fps	13 fps	0.0005
input	50k	4 fps	5 fps	0.0002
hill	30k	2 fps	3 fps	0.0001
layers	60k	1.2 fps	3.4 fps	0.0002

- 5 categories / 5 different types of scenes
- material with different properties
- stability
- wetness system
- slide, movement

Results



Conclusion and Future Work

Conclusion

- wetness in terrain erosion, soil like material

Future Work

- natural input
- real time simulation
- drying of wet material
- underlying caves and water

Acknowledgement

- Michal Chládek and Juraj Onderik – SPH

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- ...

Thank you for your
attention

